Attached document 1 (Initial parameters)

This document is an attachment to JXC※-OMZ0004, the operation manual for ACTController 2.

The initial value of the Extended function parameters

・LEF

Part Number	Explanatory note	Origin parameter	Extended function parameters						
		ORIG direction	ORIG direction (Coordinate system changed)	JOG speed Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]	
LEFS*	-	2	1	*Minimum speed for each product specification	10	3	1000	100	
LEFS*R*	Motor parallel type		2						
LEFS*L*									
LEFB*	Belt type		1						

・LEY

Part Number	Explanatory note	Origin parameter	Extended function parameters						
		ORIG direction	ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEY*	-	2	2	10	20	1	3	1000	100
LEYG*	-								
LEY*D*	Motor straight		1						
LEYG*D*									

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Part Number	Explanatory note	Origin parameter	Extended function parameters						
		ORIG direction	ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEG*MDGB	Motor straight	2	1	10	20	1	3	500	100
LEG*MGB	-		2						

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Part Number	Explanatory note	Origin parameter	Extended function parameters						
		ORIG direction	ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEHZ*	-	2	1	*Minimum speed for each product specification	20	1	3	1000	100
LEHZ*L*	Motor parallel type								
LEHF*	-								
LEHS*	-								
LEHS*L*	Motor parallel type								

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Part Number	Explanatory note	Origin parameter ORIG direction	Extended function parameters ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication Speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEKFS*	-	2	1	Minimum speed for each product specification		10	3	1000	100
LEKFS*R*	Motor parallel type		2						
LEKFS*L*									

· LEL

Part Number	Explanatory note	Origin parameter ORIG direction	Extended function parameters ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEL*	-	2	2	100	48	10	3	1000	100

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Part Number	Explanatory note	Origin parameter ORIG direction	Extended function parameters ORIG direction (Coordinate system changed)	JOG speed Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEMB*	-	1	2	Minimum speed for each product specification	12	3	1000	100
LEMB*U*	-	2						
LEMC*	-	2						
LEMC*LU*	Motor parallel type							
LEMC*U*	-	1						
LEMC*L*	Motor parallel type							
LEMH*	-	2						
LEMH*LU*	Motor parallel type							
LEMH*UT	-	1						
LEMH*LT	Motor parallel type							

· LEP

Part Number	Explanatory note	Origin parameter — ORIG direction	Extended function parameters — ORIG direction (Coordinate system changed)	JOG speed Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LEPS*J	-	2	1	20	5	3	1500	100
LEPS*LJ	Motor parallel type							
LEPY*J	-							
LEPY*LJ	Motor parallel type							
LEPS*K	-			10				
LEPS*LK	Motor parallel type							
LEPY*K	-							
LEPY*LK	Motor parallel type							

· LER

Part Number	Explanatory note	Origin parameter — ORIG direction	Extended function parameters — ORIG direction (Coordinate system changed)	JOG speed Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LER*-□*	Nil	2	1	Minimum speed for each product specification	1	3	1000	100
LER*-1*	Continuous rotation specification	1						
LER*-2*	With external stopper	2						
LER*-3*								

· LESH

Part Number	Explanatory note	Origin parameter — ORIG direction	Extended function parameters — ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LESH*L*	Motor parallel type	2	2	2	20	1	3	500	100
LESH*R*									
LESH*D*			1						

・LESYH

		Origin parameter	Extended function parameters						
Part Number	Part Number	ORIG direction	ORIG direction (Coordinate system changed)	JOG speed [mm/s]	Safe speed LIM [mm/s]	Fixed distance [mm]	Communication speed	JOG Accel/Decel [mm/s]	JOG force [%]
LESYH*D*EB	Motor straight	2	1	10	20	1	3	1000	100
LESYH*D*EC	Motor straight			5					
LESYH*D*EA	Motor straight			20					
LESYH*REA	Motor parallel type		2	20					
LESYH*REB				10					
LESYH*REC				5					
LESYH*LEA				20					
LESYH*LEB				10					
LESYH*LEC				5					

*For the minimum speed of each product specification, check the JOG speed parameter in "Extended Function Parameters".